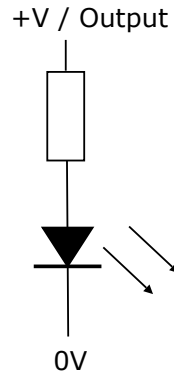


# OUTPUT

## LED

Diagram:



Function:

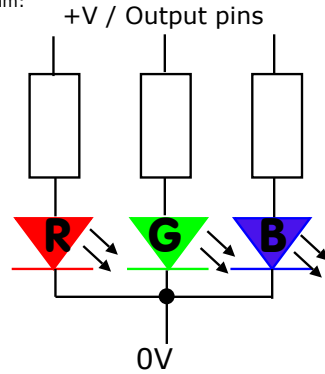
The LED is lit when connected to +V or is driven high by a microcontroller output.

The value of the resistor is found using  $V=IxR$ .

# OUTPUT

## RGB LED

Diagram:



Function:

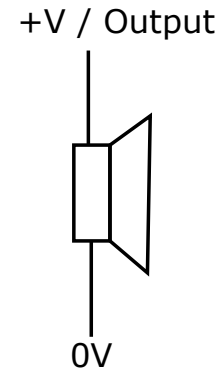
The LEDs are lit when connected to +V or is driven high by a microcontroller output. Varying brightness can be produced by using PWM from a microcontroller.

The value of the resistor is found using  $V=IxR$ .

# OUTPUT

## Speaker

Diagram:



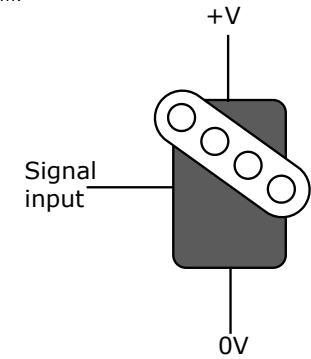
Function:

A transistor or interface drive may be required to operate some speakers.

# OUTPUT

## Servo motor 180° rotation

Diagram:



Function:

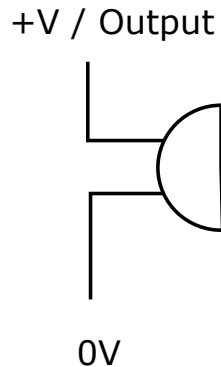
This is a standard RC servo motor, the supply voltage is 5V/6V but needs at least 250mA.

This servo can be positioned at any angle between 0° and 180°, a linkage is fastened to the axle.

# OUTPUT

## Buzzer

Diagram:



Function:

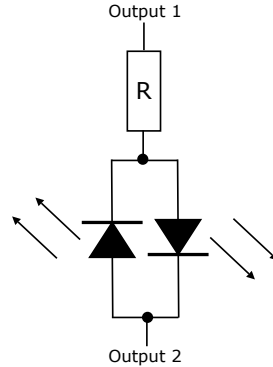
The buzzer sounds when connected to +V or driven high by a microcontroller output.

Buzzers only make a single note and aren't suitable for music, a piezo transducer is required for this.

# OUTPUT

## Bi-coloured LED

Diagram:



Function:

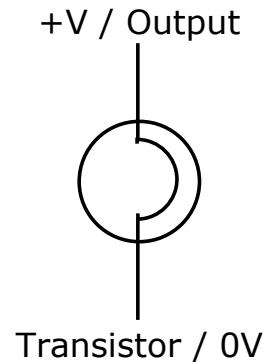
The right hand LED is lit when output 1 is +V or high and output 2 is 0V or low. The opposite values light the left hand LED.

The value of the resistor needs to be calculated using  $V=IxR$

# OUTPUT

## Bulb

Diagram:



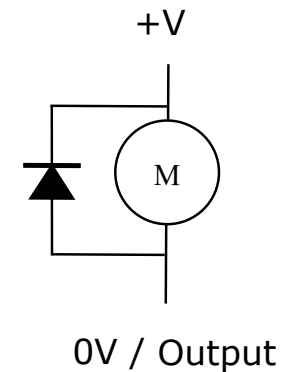
Function:

A transistor or interface driver may be required to operate some bulbs.

# OUTPUT

## DC Motor

Diagram:



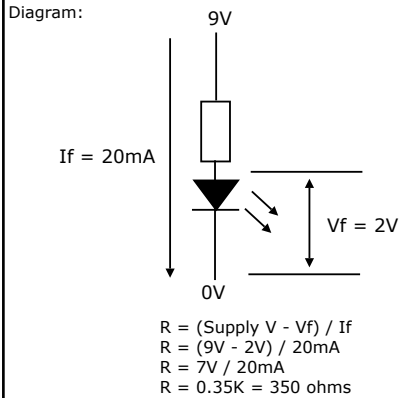
Function:

A transistor or interface driver is needed to operate motors. The 'flyback' diode is required due to the back emf produced by the motor.

The **ULN2803A** or **ULN2003A** don't need them as they already have them built in.

# OUTPUT

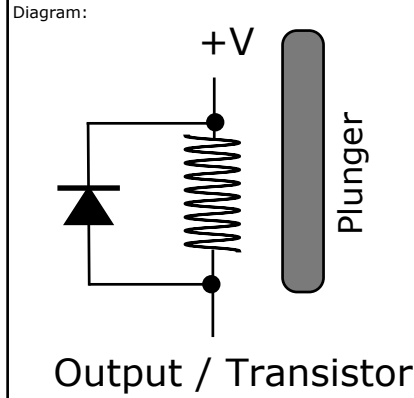
## LED Resistor Calculation



Function:  
**Supply V** is the power supply voltage  
**Vf** is the forward voltage needed to make the LED light  
**If** is the maximum current the LED can safely conduct

# OUTPUT

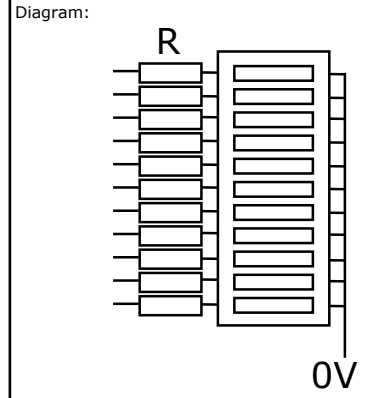
## Solenoid



Function:  
 The LEDs are lit when connected to +V or is driven high by a microcontroller output. Varying brightness can be produced by using PWM from a microcontroller.  
 The value of the resistor is found using  $V=IxR$ .

# OUTPUT

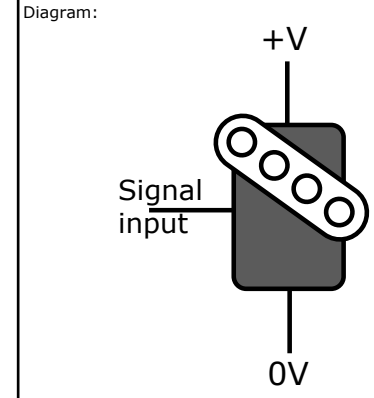
## LED Bar



Function:  
 This display has 10 LEDs in it, it is connect in common cathode mode. The 10 inputs are driven from a microcontroller or a logic circuit, +V or high lights an LED. It can be wired in common anode mode if needed.  
 The value of the resistors are calculated using  $V=IxR$

# OUTPUT

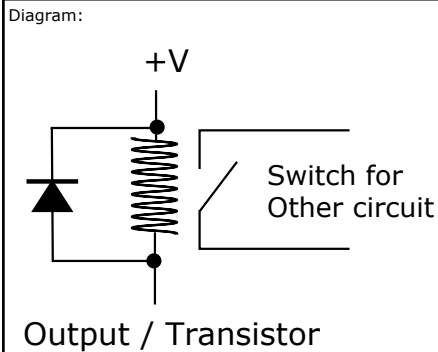
## Servo motor 360° rotation



Function:  
 This is a special RC servo motor adapted to have continuous 360°, the supply voltage is 5V/6V but needs at least 250mA.  
 This servo can be used as drive motors for Robots, it needs a microcontroller to control it effectively.

# OUTPUT

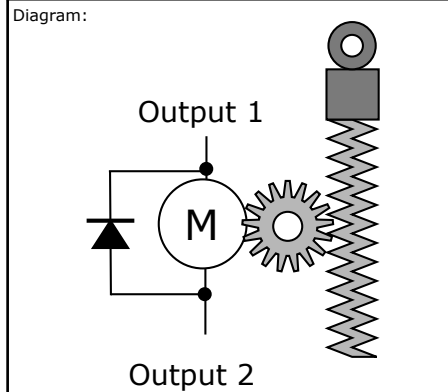
## Relay



Function:  
 The relay coil when energised cause the switch contact to close, operating the circuit connect to the relay switch contacts. They are used to control high current / voltage circuits from a low voltage / current system.

# OUTPUT

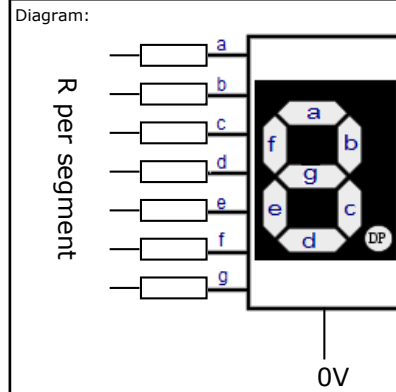
## Linear Actuator



Function:  
 The linear actuator is operated by a DC motor, and needs to have bi-directional control, to move the arm in & out.  
 The standard driver is a H-Bridge driver such as the **L293D** or **SN754410**

# OUTPUT

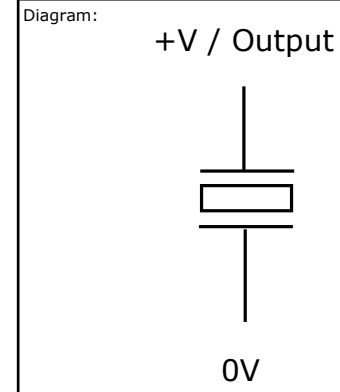
## 7 Segment display



Function:  
 This display is a common cathode type, connected to 0V. The 7 inputs are driven from a microcontroller or a logic circuit.  
 The value of the resistors are calculated using  $V=IxR$

# OUTPUT

## Piezo Transducer

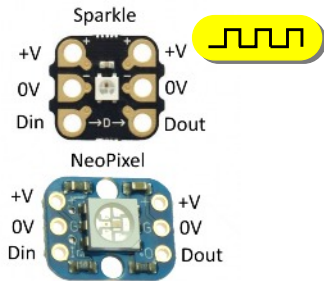


Function:  
 The Piezo transducer can be used to produce any musical note or sounds, best driven by a microcontroller.

# OUTPUT

## NeoPixels / Sparkles

Diagram:



**Note:**

You need to ensure you have a power supply with sufficient current capacity ~ 62mA per unit when fully lit

Function:

NeoPixels or Sparkles , a Red, Green and Blue LEDs alongside a driver chip into a tiny surface-mount package controlled through a single wire. They can be used individually, chained into longer strings. They need a fast microcontroller to operate them, such as Arduino. Sparkles are version that can be driven by the Crumble board.

# OUTPUT

## Graphical LCD Display

Diagram:



**Note:** There are a wide range of displays available with different resolutions ( X x Y ) and colours.

Function:

This LCD display is a large matrix of dots, which are organised in 128 x 64 dot based display. It will produce monochrome graphic and alphanumeric displays and needs to be controlled via a microcontroller and uses up to 8 outputs. They also have a backlighting for night usage.

# OUTPUT

## Alphanumeric LCD Display

Diagram:



**Note:** There are a wide range of displays available with different numbers of lines , characters per line and colours

Function:

This LCD display is a large matrix of dots, which are organised in 5x7 blocks to give an alphanumeric character based display. It needs to be controlled via a microcontroller and uses up to 8 outputs. They also have a backlighting for night usage.

# OUTPUT

## Starburst LED Display

Diagram:



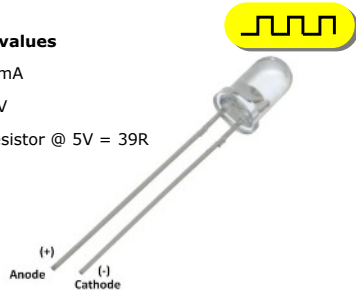
Function:

This is an **ALPHANUMERIC** display, which can display letter as well as numbers and some symbols. The display needs to be driven from a microcontroller. The value of the LED series resistors are calculated using  $V=IxR$

# OUTPUT

## IR LED 950nm

Diagram:



**Typical values**

If = 100mA

Vf = 1.5V

Series resistor @ 5V = 39R

Just like a normal LED a series resistor will be needed.

The value of the resistor is found using  $V=IxR$

Function:

This LED produces Infra Red light of 950nm wavelength, which is used in remote control applications, operating at 38KHz. It will be driven by a microcontroller to send a command via sequence of pulses. A special detector such as a TSOP38238 is needed.

# OUTPUT

## Graphical OLED Display

Diagram:



**Note:** A wide range of displays are available with many different resolutions (X x Y) and touch screens.

Function:

This type of graphical display is similar to the LCD version but offers a full colour display. It needs to be controlled using a microcontroller. They have the capacity to display full colour still and moving images, some also have touch sensitive screens for inputs etc.

# OUTPUT

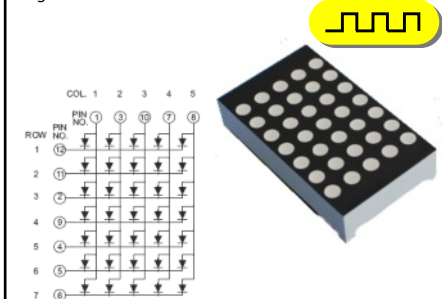
Diagram:

Function:

# OUTPUT

## 5x7 LED Dot matrix

Diagram:



**Note:** This is a Common Cathode version, Common Anode versions are available.

Function:

This display uses a matrix of 7 rows of 5 columns of LEDs. Using a microcontroller to control the rows and columns a wide range of alphanumeric characters and symbols can be displayed. The columns will need LED series resistors.